

## Definition of Symmetry of Determinants

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### Abstract

Provides a definition of symmetry for determinants, which simplifies the proof of two results for determinants.

**Keywords:** Inverse Order Number, Determinant, Transposed Determinant, Cofactor, Algebraic Cofactor.

### The Symmetry Definition of a Determinant

There are  $n^2$  numbers arranged in a table with  $n$  rows  
 $n$  columns

$$D = \begin{vmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \cdots & \cdots & \cdots & \cdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{vmatrix}$$

The  $a_{ij}$  is called the element of  $D$ , it has two subscripts.

The first subscript  $i$  is called the row subscript, and the second subscript  $j$  is called the column subscript. The row subscript  $i$  and column subscript  $j$  indicate that the element is the row  $i$  column  $j$  element of this  $D$ , for example,  $a_{21}$  is the second row first column element of  $D$ .

Make the  $n$  product of the elements located in different rows and different columns in the table  $D$ , and label it with a symbol  $(-1)^t$ , obtain the form as follows

$$(-1)^t a_{p_1 q_1} a_{p_2 q_2} \cdots a_{p_n q_n} \quad (1)$$

is called the items, which  $p_1 p_2 \cdots p_n$  is an arrangement of natural numbers  $1, 2, \dots, n$ ,  $q_1 q_2 \cdots q_n$  is also an arrangement of natural numbers  $1, 2, \dots, n$

$$t = \tau(p_1 p_2 \cdots p_n) + \tau(q_1 q_2 \cdots q_n) \quad \text{where}$$

$\tau(p_1 p_2 \cdots p_n)$  is the inverse order number of the arrangement  $p_1 p_2 \cdots p_n$ ,  $\tau(q_1 q_2 \cdots q_n)$  is the inverse order number of the arrangement  $q_1 q_2 \cdots q_n$ .

Because arrangements  $p_1 p_2 \cdots p_n$  have  $n!$  items,  $q_1 q_2 \cdots q_n$  also have  $n!$  items, so items in the form of (1)

have  $(n!)^2$  items. Algebraic sum of the  $(n!)^2$  items and division by  $n!$ , i.e

$\frac{1}{n!} \sum (-1)^t a_{p_1 q_1} a_{p_2 q_2} \cdots a_{p_n q_n} = D$  is called an  $n$

order determinant, denoted as

$$D = \begin{vmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \cdots & \cdots & \cdots & \cdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{vmatrix} =$$

$$\frac{1}{n!} \sum_{\substack{p_1 p_2 \cdots p_n \\ q_1 q_2 \cdots q_n}} (-1)^{\tau(p_1 p_2 \cdots p_n) + \tau(q_1 q_2 \cdots q_n)} a_{p_1 q_1} a_{p_2 q_2} \cdots a_{p_n q_n}$$

Where,  $a_{ij}$  as mentioned earlier, are the  $(i, j)$  elements of this determinant  $D$ , that is, the elements of the row  $i$  and column  $j$  of this determinant  $D$ .

Assuming  $i_1 \cdots i_k \cdots i_l \cdots i_n$  is a fixed arrangement, exchange  $i_k, i_l$  obtain a new fixed arrangement  $i_1 \cdots i_l \cdots i_k \cdots i_n$ , then

$$\begin{aligned} & \sum_{q_1 \cdots q_k \cdots q_l \cdots q_n} (-1)^{\tau(i_1 \cdots i_k \cdots i_l \cdots i_n) + \tau(q_1 q_2 \cdots q_n)} a_{i_1 q_1} \cdots a_{i_k q_k} \cdots a_{i_l q_l} \cdots a_{i_n q_n} \\ &= \sum_{q_1 \cdots q_l \cdots q_k \cdots q_n} (-1)^{\tau(i_1 \cdots i_l \cdots i_k \cdots i_n) + \tau(q_1 q_2 \cdots q_n)} a_{i_1 q_1} \cdots a_{i_l q_l} \cdots a_{i_k q_k} \cdots a_{i_n q_n} \end{aligned}$$

This is because each permutation changes the parity of the arrangement and the multiplication of numbers satisfies the commutative law. Pay attention to that in each of the arrangements here, has been transformed into, the arrangement has been transformed into. where the positions remain unchanged, and their values are swapped and vary with different arrangements!. It can be inferred from above that

$$\sum_{q_1 q_2 \cdots q_n} (-1)^{\tau(i_1 \cdots i_k \cdots i_l \cdots i_n) + \tau(q_1 q_2 \cdots q_n)} a_{i_1 q_1} \cdots a_{i_k q_k} \cdots a_{i_l q_l} \cdots a_{i_n q_n}$$

$$= \sum_{q_1 q_2 \cdots q_n} (-1)^{\tau(12 \cdots n) + \tau(q_1 q_2 \cdots q_n)} a_{1 q_1} a_{2 q_2} \cdots a_{n q_n}$$

$$= \sum_{q_1 q_2 \cdots q_n} (-1)^{\tau(q_1 q_2 \cdots q_n)} a_{1 q_1} a_{2 q_2} \cdots a_{n q_n}$$

This is because any  $n$  order arrangement can be transformed into  $12 \cdots n$  by a finite number of times. Also, because there are  $n!$   $n$ -order permutations in total, hence, the new determinant defined in this article is equal to the classical determinant!

This definition can be extended to row subscript as  $n$  different natural numbers and column subscript as  $n$  different natural numbers. Just arrange these  $n$  different natural numbers from small to large, then let them take values  $1, 2, \cdots, n$  in sequence!

**Example 1** Find the determinant of order  $n$

$$\begin{vmatrix} a_{11} & 0 & \cdots & 0 \\ 0 & a_{22} & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & a_{nn} \end{vmatrix}$$

**Solution** The elements  $a_{ij}$  of this determinant can be non-zero only in the case  $i = j$ , so,

$$\begin{vmatrix} a_{11} & 0 & \cdots & 0 \\ 0 & a_{22} & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & a_{nn} \end{vmatrix} =$$

$$\begin{aligned} & \frac{1}{n!} \sum_{\substack{p_1 p_2 \cdots p_n \\ q_1 q_2 \cdots q_n}} (-1)^{\tau(p_1 p_2 \cdots p_n) + \tau(q_1 q_2 \cdots q_n)} a_{p_1 q_1} a_{p_2 q_2} \cdots a_{p_n q_n} \\ &= \frac{1}{n!} \sum_{p_1 p_2 \cdots p_n} (-1)^{\tau(p_1 p_2 \cdots p_n) + \tau(p_1 p_2 \cdots p_n)} a_{p_1 p_1} a_{p_2 p_2} \cdots a_{p_n p_n} \\ &= \frac{1}{n!} \sum_{p_1 p_2 \cdots p_n} a_{p_1 p_1} a_{p_2 p_2} \cdots a_{p_n p_n} = a_{11} a_{22} \cdots a_{nn} \end{aligned}$$

**Example 2** Find the determinant of order  $n$

$$\begin{vmatrix} a_{11} & 0 & \cdots & 0 \\ a_{21} & a_{22} & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{vmatrix}$$

**Solution** When  $p_1=1$ ,  $q_1$  must be 1, otherwise

$a_{p_1 q_1}=0$ , when  $p_2=2$ ,  $q_2$  must be 2, otherwise

$a_{p_2 q_2}=0$ , and so on  $p_i=q_i, i=1, 2, \dots, n$ . The

following is the same as Example 1.

**Example 3** Find the determinant of order  $n$

$$\begin{vmatrix} 0 & \cdots & 0 & a_{1n} \\ 0 & \cdots & a_{2n-1} & 0 \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & \cdots & 0 & 0 \end{vmatrix}$$

**Solution** For this determinant, only the elements on the second diagonal may not be 0, so only it's worth considering  $q_i = n+1-p_i, i=1, 2, \dots, n$ . therefore

$$\begin{aligned} & \begin{vmatrix} 0 & \cdots & 0 & a_{1n} \\ 0 & \cdots & a_{2n-1} & 0 \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & \cdots & 0 & 0 \end{vmatrix} = \\ & \frac{1}{n!} \sum_{\substack{p_1 p_2 \cdots p_n \\ q_1 q_2 \cdots q_n}} (-1)^{\tau(p_1 p_2 \cdots p_n) + \tau(q_1 q_2 \cdots q_n)} a_{p_1 q_1} a_{p_2 q_2} \cdots a_{p_n q_n} \\ & = \frac{1}{n!} \sum_{p_1 p_2 \cdots p_n} (-1)^t a_{p_1 n+1-p_1} a_{p_2 n+1-p_2} \cdots a_{p_n n+1-p_n} \end{aligned}$$

Because each permutation changes the parity of the arrangement and the multiplication of numbers satisfies the commutative law, and any arrangement of order can be transformed into in a finite number of times, therefore

$$t = \tau(12 \cdots n) + \tau(n(n-1) \cdots 21) = \frac{n(n-1)}{2}$$

$$\begin{vmatrix} 0 & \cdots & 0 & a_{1n} \\ 0 & \cdots & a_{2n-1} & 0 \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & \cdots & 0 & 0 \end{vmatrix} = (-1)^{\frac{n(n-1)}{2}} a_{1n} a_{2n-1} \cdots a_{n1}$$

**Property** Determinant is equal to its transpose determinant. This is a direct result of the symmetry definition of determinants, and also is the best application of this new definition of determinant.

### The Expansion Theorem of Determinants by Rows (Columns)

A determinant is equal to the sum of the products of its elements and their corresponding algebraic cofactor in any row (column), that is

$$D = a_{i1}A_{i1} + a_{i2}A_{i2} + \cdots + a_{in}A_{in} \quad (i=1, 2, \dots, n)$$

$$D = a_{1j}A_{1j} + a_{2j}A_{2j} + \cdots + a_{nj}A_{nj} \quad (j=1, 2, \dots, n)$$

**Proof** Prove only for rows, because as long as it holds for rows, the above property immediately deduce that it holds for columns as well!

$$\begin{aligned} D &= \begin{vmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{vmatrix} = \\ & \frac{1}{n!} \sum_{\substack{p_1 p_2 \cdots p_n \\ q_1 q_2 \cdots q_n}} (-1)^{\tau(p_1 p_2 \cdots p_n) + \tau(q_1 q_2 \cdots q_n)} a_{p_1 q_1} a_{p_2 q_2} \cdots a_{p_n q_n} \\ & = \frac{1}{n!} \sum_{\substack{p_1 \cdots p_i \cdots p_n \\ q_1 \cdots 1 \cdots q_n}} (-1)^{\tau(p_1 \cdots p_i \cdots p_n) + \tau(q_1 \cdots 1 \cdots q_n)} a_{p_1 q_1} \cdots a_{p_i 1} \cdots a_{p_n q_n} \\ & + \frac{1}{n!} \sum_{\substack{p_1 \cdots p_i \cdots p_n \\ q_1 \cdots 2 \cdots q_n}} (-1)^{\tau(p_1 \cdots p_i \cdots p_n) + \tau(q_1 \cdots 2 \cdots q_n)} a_{p_1 q_1} \cdots a_{p_i 2} \cdots a_{p_n q_n} \\ & + \cdots \\ & + \frac{1}{n!} \sum_{\substack{p_1 \cdots p_i \cdots p_n \\ q_1 \cdots k \cdots q_n}} (-1)^{\tau(p_1 \cdots p_i \cdots p_n) + \tau(q_1 \cdots k \cdots q_n)} a_{p_1 q_1} \cdots a_{p_i k} \cdots a_{p_n q_n} \\ & + \cdots \\ & + \frac{1}{n!} \sum_{\substack{p_1 \cdots p_i \cdots p_n \\ q_1 \cdots n \cdots q_n}} (-1)^{\tau(p_1 \cdots p_i \cdots p_n) + \tau(q_1 \cdots n \cdots q_n)} a_{p_1 q_1} \cdots a_{p_i n} \cdots a_{p_n q_n} \end{aligned}$$

$$\begin{aligned}
& \frac{1}{n!} \sum_{\substack{p_1 \cdots p_i \cdots p_n \\ q_1 \cdots k \cdots q_n}} (-1)^{\tau(p_1 \cdots p_i \cdots p_n) + \tau(q_1 \cdots k \cdots q_n)} a_{p_1 q_1} \cdots a_{p_i k} \cdots a_{p_n q_n} \\
&= \frac{1}{n!} \sum_{\substack{p_1 p_i \cdots p_{i-1} p_{i+1} \cdots p_n \\ k q_1 \cdots q_{i-1} q_{i+1} \cdots q_n}} (-1)^{t_i} a_{p_1 k} a_{p_i q_1} \cdots a_{p_{i-1} q_{i-1}} a_{p_{i+1} q_{i+1}} \cdots a_{p_n q_n} \\
&+ \frac{1}{n!} \sum_{\substack{p_1 p_i p_2 \cdots p_{i-1} p_{i+1} \cdots p_n \\ q_1 k q_2 \cdots q_{i-1} q_{i+1} \cdots q_n}} (-1)^{t_2} a_{p_1 q_1} a_{p_i k} a_{p_2 q_2} \cdots a_{p_{i-1} q_{i-1}} a_{p_{i+1} q_{i+1}} \cdots a_{p_n q_n} \\
&+ \cdots \\
&+ \frac{1}{n!} \sum_{\substack{p_1 p_2 \cdots p_{i-1} p_{i+1} \cdots p_n \\ q_1 q_2 \cdots q_{i-1} k q_{i+1} \cdots q_n}} (-1)^{t_j} a_{p_1 q_1} a_{p_2 q_2} \cdots a_{p_{i-1} q_{i-1}} a_{p_i k} a_{p_{i+1} q_{i+1}} \\
&\cdots a_{p_n q_n} \\
&+ \cdots \\
&+ \frac{1}{n!} \sum_{\substack{p_1 p_2 \cdots p_{i-1} p_{i+1} \cdots p_n p_j \\ q_1 q_2 \cdots q_{i-1} q_{i+1} \cdots q_n k}} (-1)^{t_n} a_{p_1 q_1} a_{p_2 q_2} \cdots a_{p_{i-1} q_{i-1}} a_{p_{i+1} q_{i+1}} \\
&\cdots a_{p_n q_n} a_{p_i k}
\end{aligned}$$
$$\begin{aligned} t_1 &= \tau(p_i p_1 \cdots p_{i-1} p_{i+1} \cdots p_n) \\ &\quad + \tau(k q_1 q_2 \cdots q_{i-1} q_{i+1} \cdots q_n) \\ t_s &= \tau(p_1 \cdots p_i \cdots p_{i-1} p_{i+1} \cdots p_n) \\ &\quad + \tau(q_1 \cdots k \cdots q_{i-1} q_{i+1} \cdots n) \\ s &= 2, \dots, n, i > 1, \end{aligned}$$

Because each permutation changes the parity of the arrangement and the number  $s$  of digits from  $p_1$  to  $p_i$  is equal to the number of digits from  $q_1$  to  $k$ , therefore

$$\begin{aligned}
& \frac{1}{n!} \sum_{\substack{\beta_1 \beta_1 \dots \beta_{i-1} \beta_{i+1} \dots \beta_n \\ k q_1 \dots q_{i-1} q_{i+1} \dots q_n}} (-1)^{t_1} a_{\beta_1 k} a_{\beta_1 q_1} \dots a_{\beta_{i-1} q_{i-1}} a_{\beta_{i+1} q_{i+1}} \dots a_{\beta_n q_n} \\
&= \frac{1}{n!} \sum_{\substack{\beta_1 \beta_1 \beta_2 \dots \beta_{i-1} \beta_{i+1} \dots \beta_n \\ q_1 k q_2 \dots q_{i-1} q_{i+1} \dots q_n}} (-1)^{t_2} a_{\beta_1 q_1} a_{\beta_1 k} a_{\beta_2 q_2} \dots a_{\beta_{i-1} q_{i-1}} a_{\beta_{i+1} q_{i+1}} \\
&\dots a_{\beta_n q_n} \\
&= \dots = \\
& \frac{1}{n!} \sum_{\substack{\beta_1 \beta_2 \dots \beta_{i-1} \beta_i \beta_{i+1} \dots \beta_n \\ q_1 q_2 \dots q_{i-1} k q_{i+1} \dots q_n}} (-1)^{t_i} a_{\beta_1 q_1} a_{\beta_2 q_2} \dots a_{\beta_{i-1} q_{i-1}} a_{\beta_i k} a_{\beta_{i+1} q_{i+1}} \dots a_{\beta_n q_n} \\
&= \dots = \\
& \frac{1}{n!} \sum_{\substack{\beta_1 \beta_2 \dots \beta_{i-1} \beta_{i+1} \dots \beta_n \beta_i \\ q_1 q_2 \dots q_{i-1} q_{i+1} \dots q_n k}} (-1)^{t_n} a_{\beta_1 q_1} a_{\beta_2 q_2} \dots a_{\beta_{i-1} q_{i-1}} a_{\beta_{i+1} q_{i+1}} \dots a_{\beta_n q_n} \\
&\cdot a_{\beta_i k} \\
&= \frac{1}{n!} a_{\beta_i k} (-1)^{\beta_i + k} \sum_{\substack{\beta_1 \dots \beta_{i-1} \beta_{i+1} \dots \beta_n \\ q_1 \dots q_{i-1} q_{i+1} \dots q_n}} (-1)^{t_i} a_{\beta_1 q_1} \dots a_{\beta_{i-1} q_{i-1}} a_{\beta_{i+1} q_{i+1}} \\
&\dots a_{\beta_n q_n}
\end{aligned}$$

$$\begin{aligned} & \frac{1}{n!} \sum_{\substack{p_1 \cdots p_n \\ q_1 \cdots q_n}} (-1)^{\tau(p_1 \cdots p_n) + \tau(q_1 \cdots q_n)} a_{p_1 q_1} \cdots a_{p_i q_i} \cdots a_{p_n q_n} \\ &= \frac{n}{n!} a_{p_i q_i} (-1)^{p_i + k} \sum_{\substack{p_1 \cdots p_{i-1} p_{i+1} \cdots p_n \\ q_1 \cdots q_{i-1} q_{i+1} \cdots q_n}} (-1)^{t_i} a_{p_1 q_1} \cdots a_{p_{i-1} q_{i-1}} a_{p_{i+1} q_{i+1}} \\ & \quad \cdots a_{p_n q_n} \\ &= \frac{1}{(n-1)!} a_{p_i q_i} (-1)^{p_i + k} (n-1)! M_{p_i k} = a_{p_i k} A_{p_i k} \end{aligned}$$
$$t_i = \tau(p_1 \cdots p_{i-1} p_{i+1} \cdots p_n) + \tau(q_1 \cdots q_{i-1} q_{i+1} \cdots q_n)$$
$$D = \begin{vmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \cdots & \cdots & \cdots & \cdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{vmatrix} =$$

The theorem has been proven!

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## Reference

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