

Journal of Autonomous Vehicles, Drones, and Intelligent Mobility

Cyber-Physical Systems for Enhancing Precision and Efficiency in 3D Concrete Printing

Mesoudy M El 1*, Foulki R2 & Amegouz D1

¹LTSI Laboratory, Sidi Mohamed Ben Abdellah University, Fes, Morocco ²Civil Department, Moulay Ismail University, Meknes, Morocco

*Corresponding author: Mesoudy M El, LTSI Laboratory, Sidi Mohamed Ben Abdellah University, Fes, Morocco.

Submitted: 03 November 2025 Accepted: 11 November 2025 Published: 18 November 2025

doi https://doi.org/10.63620/MKJAVDIM.2025.

Citation: Mesoudy, M. EI., Foulki, R., Amegouz, D., A., (2025). Cyber-Physical Systems for Enhancing Precision and Efficiency in 3D Concrete Printing. J of Aut Veh Dro and Int Mob, 1(2), 01-06.

Abstract

The construction industry lags in adopting automation compared to other sectors, continuing to face challenges such as inefficiency and quality inconsistencies. 3D Concrete Printing (3DCP) has emerged as a ground-breaking technology, offering advantages like improved speed, design flexibility, and reduced waste. Despite its potential, 3DCP encounters issues with process precision and scalability. This research proposes integrating Cyber-Physical Systems (CPS) into 3DCP to address these challenges. The CPS framework employs real-time sensing, data processing, and feedback control to monitor and adjust key parameters during printing. By utilizing advanced algorithms and adaptive mechanisms, CPS ensures precision, minimizes material waste, and enhances scalability. Validation and testing confirm significant improvements in layer consistency and automation. This work contributes to developing smart, efficient 3DCP processes suitable for large-scale applications and sets the stage for future AI-driven enhancements in real-world construction environments.

Keywords: Cyber-Physical Systems, 3D Concrete Printing, Concrete Additive Manufacturing, Automation in Construction, Real-Time Monitoring, Smart Construction.

Introduction

In a world where automation, robotics and artificial intelligence are revolutionizing nearly every industry sector, the construction field remains one of the few still largely reliant on conventional and manual methods. In fact, despite advancements in manufacturing and automation technologies, construction continues to face challenges such as labor shortages, inefficiencies, and inconsistencies in quality.

However, today, one of the most innovative technologies is beginning to reshape the future of construction. This technology is known as 3D Concrete Printing (3DCP) and actually promises a groundbreaking shift from traditional construction methods to print and build with concrete by using automated systems.

The 3DCP process relies on three main units. The first unit prepares the material and transfers it to the second unit, the print

head, which is responsible for depositing the concrete layer by layer to achieve the desired shape. The third unit is the control unit, which, based on a virtual model, creates the movement path of the print head with an appropriate printing speed and extrusion rate. Additionally, various 3D printing methods have been developed, such as contour crafting and D-Shape [1].

Despite offering numerous advantages, including greater design flexibility, improved construction speed, and a reduction in material waste, 3DCP still faces challenges related to process control and precision, especially in large-scale applications [2]. To address these issues, the integration of Cyber-Physical Systems (CPS) into 3DCP is proposed as a promising solution.

by using CPS, the precision, efficiency, and scalability of 3D concrete printing may be greatly increased. In fact, CPS connects the digital and physical worlds and enables real-time data

monitoring and feedback control. CPS has also the ability to raise performance standards in the construction sector by employing automation and intelligent technology [3, 4].

This works aims to investigate the integration of CPS into 3DCP to enhance process precision, real-time adaptability, and scalability. Specifically, the study focuses on how CPS can optimize key parameters during printing, ensure quality control, and enable predictive maintenance. By addressing these aspects, this research aims to contribute to the development of a highly efficient and automated 3DCP process, suitable for large-scale, complex construction projects.

Each section of the paper contributes to a comprehensive grasp of the methodology, execution, and advantages of this integration:

The first section 'State-of-the-Art Review'

provides a summary of 3DCP technology and CPS, outlining their development, uses, and collaboration. The conversation highlights the impactful potential of combining CPS with 3DCP to enhance process dependability, effectiveness, and flexibility [5].

This part Secondly, the 'Methodology and Approach' section Secondly the 'Methodology and Approach' section describes the components of the 3DCP process, such as material preparation, printing, and control units. It presents a CPS framework designed for the self-monitoring of a multi-dimensional extrusion nozzle, featuring advancements such as real-time data collection, processing, and control for dynamic modifications.

The third section 'Key Benefits and Applications' elaborates on the advantages of integrating CPS in 3DCP, such as improved accuracy, real-time management, automation, and scalability. It investigates the capability of CPS to coordinate several robotic arms for reinforcement and curing activities, setting the foundation for intelligent construction sites.

Through this structured exploration, the paper aims to offer insights into the real-world use of CPS in 3DCP, emphasizing its ability to transform construction methods while tackling obstacles in automation, material optimization, and process efficiency.

State-of-the-Art Review The 3DCP Technology

3D Printing (3DP), also known as Additive Manufacturing (AM), is a revolutiannary technology regouping multiple production techniques first introduced in the mid-1980s. These techniques fabricates physical objects from geometrical representations by successively adding material layer by layer, guided by computer-aided design (CAD) models. Charles Hull commercialized the first 3D printing process in 1980, and since then, the technology has experienced remarkable growth gaining traction within 8 sectors like automotive, aerospace, and medicine [6-8].

3D printing's versatility and potential open new opportunities across industries, inspiring construction field specialists to invest in 3DP and explore its potential to revolutionize building and architectural practices. The first significant attempt can be attributed to Behrokh Khoshnevis, who introduced a concrete printing method called Contour Crafting. Shortly after, a new powder-based technique was developed and later named the D-Shape technique. Since these pioneering efforts, research has continued to advance 3DCP, focusing on enhancing precision, scalability, and efficiency.

The main 3DCP process can be described as a method where concrete is deposited layer by layer to construct a structure directly from a digital model, eliminating the need for traditional formwork, [9]. This process is typically implemented using two types of structural systems: gantry systems and 6-axis robotic arms (Fig. 1).

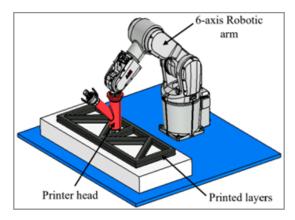


Figure 1: 3D Concrete Printing Using 6-Axis Robotic arm

Today, recent developments include integrating robotics, automation, and advanced materials, which have propelled 3DCP into a promising technology for large-scale applications. Researchers are investigating various deposition methods, control systems, and material formulations to overcome challenges such as structural integrity, process consistency, and environmental adaptability. These continuous efforts aim to push the boundaries of 3DCP, transitioning it from laboratory settings to real-world construction environments [10].

CPS in Construction and Other Industries

Cyber-physical systems (CPS) are artificial networks, based on computing algorithms and computerized components, and can coordinate their action within One Network. The systems are based on capturing information, processing it, and using control loops to effect physical processes in the real world. The ubiquity of CPS is the ability to integrate the actual world and the virtual world such that the machines and devices are able to react and adjust to the environment in real time. This interaction is made possible by wireless sensors, actuators, controllers and commu-

nication networks [11-13].

In a CPS, the cyber components acquire data from the physical system through sensors and send feedback control signals to achieve shared objectives. This interaction ensures efficient

and secure operations by creating a closed-loop system where data and control signals flow seamlessly between the physical and digital domains. To further enhance this integration, Analog-to-Digital Converter (ADC) and Digital-to-Analog Converter (DAC) interfaces are essential (Fig. 2).

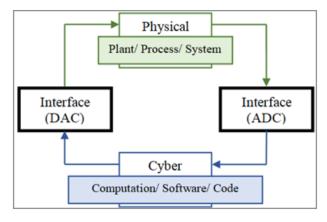


Figure 2: Structure of the CPS [14]

For instance, in power systems, integrating the physical infrastructure with a cyber layer forms a strongly coupled Cyber-Physical Power System (CPPS). This integration allows for real-time monitoring and adaptive control of the system, ensuring efficiency, reliability, and security [14].

CPS has revolutionized several industries boosting reliability, accuracy and productivity. In the case of manufacturing, CPS is regarded as the backbone of Industry 4.0: this enables the creation of smart factories where machines interact with each other and act independently to facilitate the production process [15]. In the case of automotive, CPS is critical to the design of self-driving cars — where realtime response with the surroundings in context of control and navigation is required [16]. Similar to automobiles, in the case of healthcare, medical devices and systems use CPS to autonomously monitor patients and provide them with individualized treatment [17]. The continuous evolution of technologies such as machine learning, IoT, and others allow CPS to remain at the forefront of change in a multitude of industry applications [18].

When it comes to the construction industry, CPS is ensuring the speeding up of the building and construction process in a safe manner [19, 20]. This technology achieves objectives such as 3DCP with far more accuracy through the use of real-time sensing, gathering, and processing data, along with adaptive control. For instance, CPS monitors extrusion flow rate, layer thickness, and the environment and makes the necessary corrections in real time. Moreso, we can use CPS for predictive maintenance inorder to reduce the downtime of the equipment and increase the equipment availability. Constructing and embedding CPS into construction processes, for the project, means accomplishing more with less money and fewer risks in terms of injury, which means changing how the buildings and infrastructures in general are built and designed.

Methodology and Approach

3DCP Process Review

Based of the main concept of 3DCP techniques, our printing process is built around three primary units:

Material Preparation Unit: This unit is responsible for mixing and conditioning the concrete to achieve the necessary flowability and setting properties. The material is then transported to the deposition system. The preparation, mixing and pumping systeme used on our process is the M-Tec duo mix Connect pump [21].

Printing Unit: This includes the print head and the deposition system, where the concrete is extruded through a nozzle to create successive layers. The main structure employed for the printing operation is the Gantry Systems which allows precise movement of the print head along the x, y, and z axes, making them suitable for printing large-scale structures.

Control Unit: This unit ensures the synchronization of all components and generates the motion trajectory of the print head based on the virtual CAD model. It also manages the extrusion rate and layer height to maintain consistency.

Morever, three crucial steps are included in the 3DCP Process.

- 1. **Digital Model Design:** The process begins with creating a 3D CAD model of the desired structure. This model is then converted into a series of instructions (G-code) for the printer.
- **2. Material Deposition:** The prepared concrete is deposited layer by layer in a controlled manner, with each layer bonding to the previous one to form a cohesive structure.
- Curing and Hardening: After deposition, the material undergoes curing to achieve the required strength and durability.

CPS Framework for 3DCP

3D concrete printing is considered as a multi-variable process with numerous parameters influencing the printing process, from print speed and deposition rate to nozzle shape and printing path. This is why the use of CPS can offer greater flexibility, control, and precision.

In 3DP, the CPS framework integrates a set of key components, such as sensors, controllers, processors and actuators which

interact to create a cohesive system. The adaptation of such a framework in 3DCP could enable not only real-time monitoring of concrete extrusion and layer formation, but olso aims ensuring dimensional accuracy and reducing material wastes.

The proposed methodology deals with incorporating CPS for self-monitoring of a multi-dimension extrusion nozzle, which has been specially designed to change its extrusion diameter while printing (Fig. 3). Although previous works have looked at designs of nozzles that are adjustable [22-24], this work incorporates an era of novel approaches which is the use of CPS in the real time control of the nozzles. This integration allows for appropriate adjustments to be made to the dimensions of the nozzle with regard to the information received from the sensors and their adaptive feedbacks thus improving the process and preparing for optimal layer deposition for the entire 3DCP process.

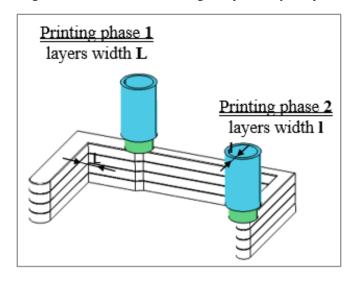


Figure 3: The variable Nozzle Printing Operation Process

Data Collecting and Sensing Mechanisms

For our CPS system, sensors are quite cricial for real-time monitoring as they can provide data on printing parameters such as flow rate, layer form and height and environmental conditions like temperature and humidity.

By employing a comprehensive array of sensors, the system guarantees high-resolution tracking of both the nozzle's performance and environmental conditions, allowing for real-time adjustments and accuracy in 3D concrete printing. To collect accurate data, each sensor must be positioned in a specific location according to its role; for example, flow and speed sensors are placed on the print head, while environmental factor sensors are positioned within the printing area.

The framework of this work integrates three types of sensors to enhance the precision and adaptability of the 3D concrete printing process:

Extrusion Rate Sensors: embedded within the extrusion system to control the concrete material's flow rate according to the size of the extrusion nozzle. They guarantee that the material is extruded at a steady pace, avoiding both over-extrusion and under-extrusion.

Width Measurement Sensors: Positioned near the nozzle exit, these sensors measure the width of the extruded layers in real-time. By comparing the actual layer width to the desired dimensions, the system can detect deviations and adjust the nozzle extrusion diameter to maintain dimensional accuracy.

Environmental Sensors: These sensors are placed strategically around the printing environment to monitor external factors like ambient temperature, humidity, and wind speed.

Collectively, these sensors create an integrated network that supplies the CPS framework with essential data for immediate

analysis and management, guaranteeing a strong and dependable printing operation.

The second part of the CPS framework is the data acquisition Process that can involve continuous data streaming, periodic sampling, or sensor fusion techniques to enhance accuracy.

Data acquisition is central to the CPS framework, linking the physical and digital domains of 3D concrete printing. Sensors for extrusion rate, width measurement, and environmental conditions generate analog signals, which are converted into digital data via ADC interfaces. This digital format enables real-time analysis and precise adjustments.

Data Processing and Control Algorithms

The data processing and analysis phases are essential for transforming raw sensor data into actionable insights within the CPS framework. Once the data is acquired and digitized, advanced algorithms process it to detect anomalies, monitor trends, and predict deviations in key parameters such as extrusion rate and layer width.

For the incoming data processing step, machine learning algorithms for predictive analysis, enables the system adjust parameters in response to variations detected during the printing process [25, 26].

Machine learning models and predictive analytics are used to examine intricate data patterns, allowing the system to adjust to evolving conditions throughout the printing process.

As for the Control Algorithms, feedback mechanisms or algorithms will be implemented. For example, if the layer width deviates, a control system could modify the nozzle's position

and flow rate to ensure uniformity by transmitting signals to the actuators of the system.

Following data processing and analysis, actuators and adaptive control systems are necessary, as these components react to the collected data to modify or adjust the printing parameters through DAC interfaces.

Feedback control systems use the analyzed data to modify extrusion speeds, nozzle placements, and environmental conditions instantly, guaranteeing accuracy and uniformity.

Furthermore, to facilitate effective real-time modifications, the CPS system might incorporate a Proportional-Integral-Derivative (PID) controller or a more sophisticated model predictive control.

System Validation and Testing

Positioning the sensors, processing the data, programming the algorithms, and activating the control mechanism are all parts of the CPS framework designed for 3DCP. The final remaining step is system validation through testing and simulation in a virtual environment before live printing. Experimental testing are also required to evaluate the CPS performance.

Key Benefits and Applications Application of CPS

The suggested CPS framework with the self-monitoring extrusion system improves the reliability of the 3D concrete printing process through the incorporation of smart data management, facilitating scalable and flexible operations across different construction settings. This advancement guarantees immediate modifications, enhanced accuracy, and effectiveness, laying the foundation for intelligent and smart building methods.

To enhance this model further, the framework may be expanded to incorporate a CPS that can manage two robotic arms working concurrently during printing. The initial robotic arm would place reinforcement rebars, an essential process for maintaining the structural stability of large-scale printed components.

The additional robotic arm would manage the heating and curing process of newly printed concrete layers, enhancing material characteristics and decreasing setting duration.

By aligning these robotic arms with the CPS, the system could enhance the collaboration among extrusion, reinforcement placement, and curing. This integration would allow for the creation of more intricate shapes and stable components, establishing a new benchmark for automation in 3D concrete printing.

Benefits : Precision and Real-Time control

The CPS framework improves the accuracy of 3D concrete printing by identifying and adjusting for deviations in real time. Sensors track factors such as extrusion rate and layer width, allowing for prompt modifications to ensure consistency and structural stability. Predictive algorithms enhance precision, reducing material waste and guaranteeing compliance with design specifications.

Benefits: Automation and Scalability

The CPS framework improves automation in 3D concrete printing, managing intricate operations as layer creation and extrusion rate control. It also facilitates scalable operations, permitting the creation of both small and large structures by accurately modifying the shape and size of printed layers. Moreover, the system facilitates self-adjustment for curved and rounded paths, guaranteeing precise and seamless deposition along non-linear trajectories.

Benefits: Potential in Smart Construction Sites

CPS paves the way for a more for a more cohesive smart construction environment, where machines and human operators collaborate together effortlessly By integrating with Building Information Modeling (BIM) systems, CPS facilitates real-time updates, flexible modifications to construction plans, and enhancement of workflows. This integration improves efficiency, minimizes mistakes, and fosters a more flexible approach to construction processes, resulting in smarter construction sites that quickly adapt to changing needs [27].

Conclusion and Outlook

This study showcases the transformative ability of incorporating CPS into 3DCP, tackling issues related to precision, real-time responsiveness, and scalability. The suggested CPS framework improves process precision through the use of sensor networks, adaptive feedback systems, and predictive algorithms. A significant advancement in this framework is the creation of a flexible extrusion nozzle that can change its size in real-time throughout the printing process. This feature enables ideal layer application, guaranteeing uniformity and accuracy in intricate shapes and different structural needs. Through the automation of intricate processes, such as this adjustable nozzle mechanism, and by facilitating scalability across various construction projects, the integration sets the stage for more intelligent and efficient construction techniques.

The results prompt a wider conversation regarding the future of CPS in construction, especially its significance in establishing completely autonomous and interconnected intelligent construction sites. Future studies may investigate the integration of artificial intelligence (AI) to further improve decision-making abilities, predictive analytics, and self-optimization in 3DCP processes. Algorithms powered by AI, when integrated with CPS, have the potential to transform collaborative multi-robot systems, allowing for more intricate designs, quick adjustments to varying conditions, and smooth incorporation into Building Information Modeling (BIM) frameworks.

This research lays a strong groundwork for future advancements in construction technology by addressing gaps in automation, precision, and adaptability, establishing CPS as an essential facilitator of Industry 4.0 within the construction industry.

Acknowledgement

In this section, I would like to thank the Research Institute for Solar Energy and New Energies (IRESEN) and the University Sidi Mohamed Ben Abdellah (USMBA) for funding this work.

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